

Real-Time Interaction

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Interaction

Interaction

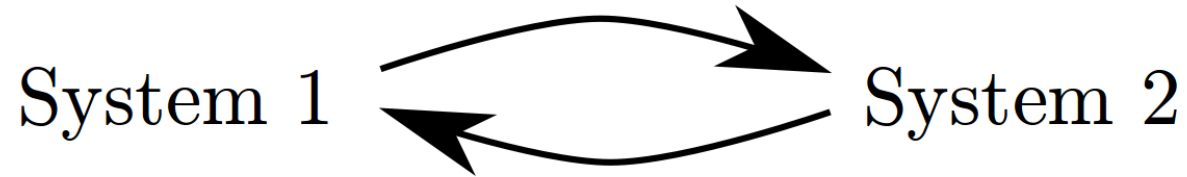
From Oxford dictionary

Reciprocal action or influence

Interaction

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Reciprocal action or influence



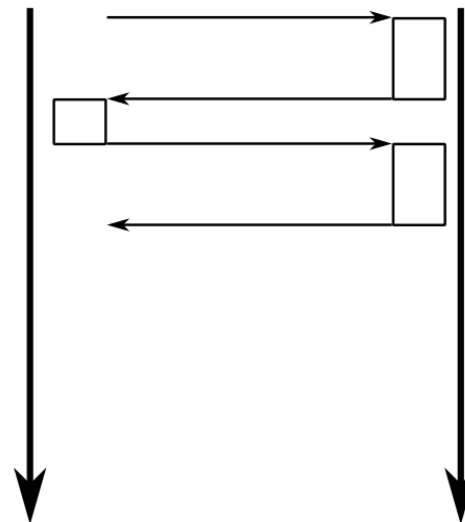
Interaction

From Oxford dictionary

Reciprocal action or influence

System 1

System 2



Time

Sequence diagram

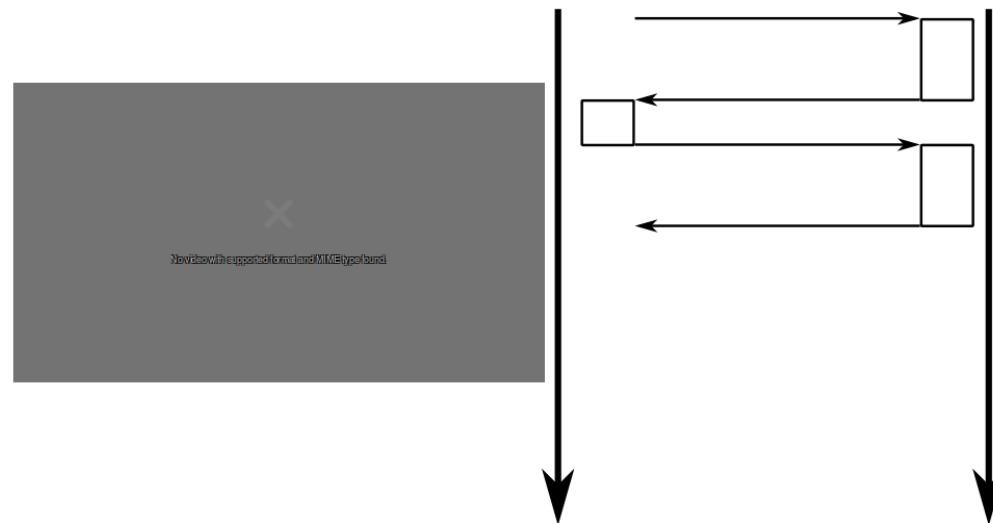
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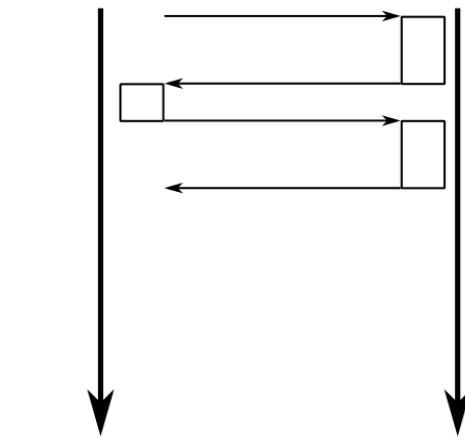
Real-Time Interaction

From Oxford dictionary

Reciprocal action or influence

System 1

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Sequence diagram

Real-Time

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Definitions

From Cambridge dictionary

Communicated, shown,
presented, etc. at the same time
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From Wikipedia

A real-time system has been
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Real-Time

is relative to the considered events

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Real-Time

is relative to the considered events

Real-time systems have to meet deadlines!

How fast the system should respond depends on the considered situation

A real-time system maintains a continuous and timely interaction with its environment

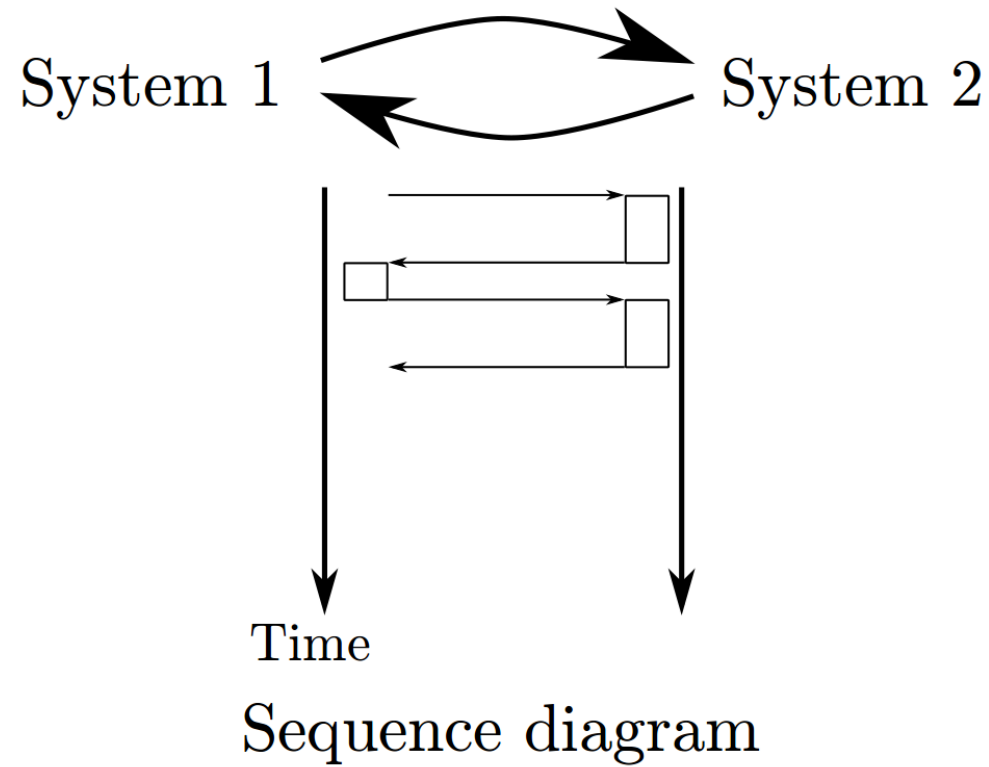
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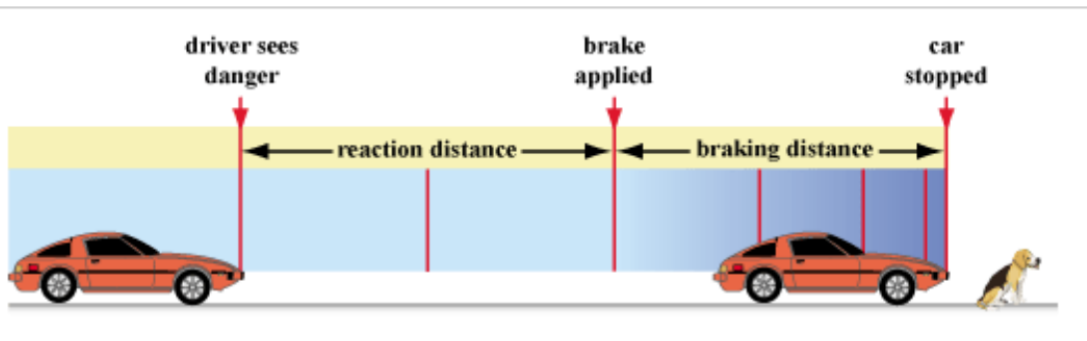
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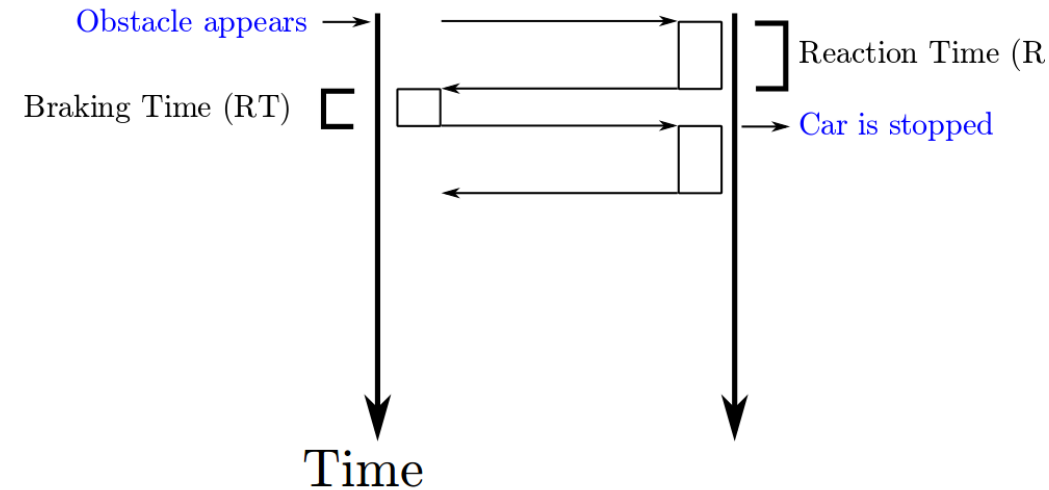
Real-Time Interaction

Example: Stopping a car



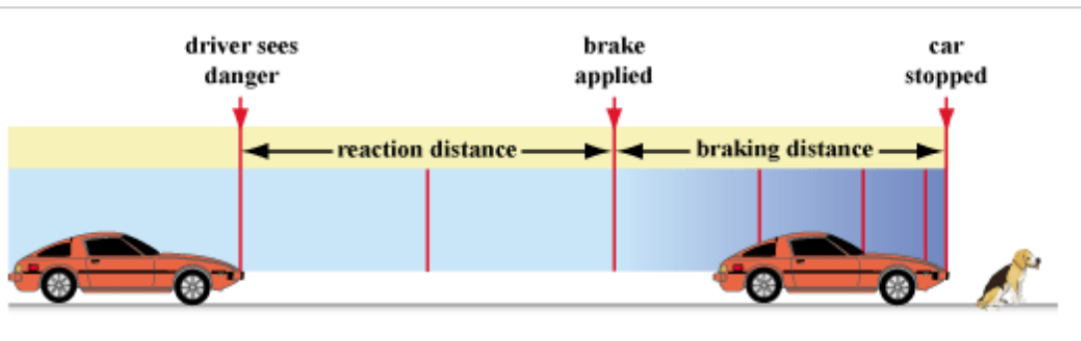
Environment

Driver



Real-Time Interaction

Example: Stopping a car



$$SD = RD + BD$$

$$SD < OD$$

$$RD = v * RT$$

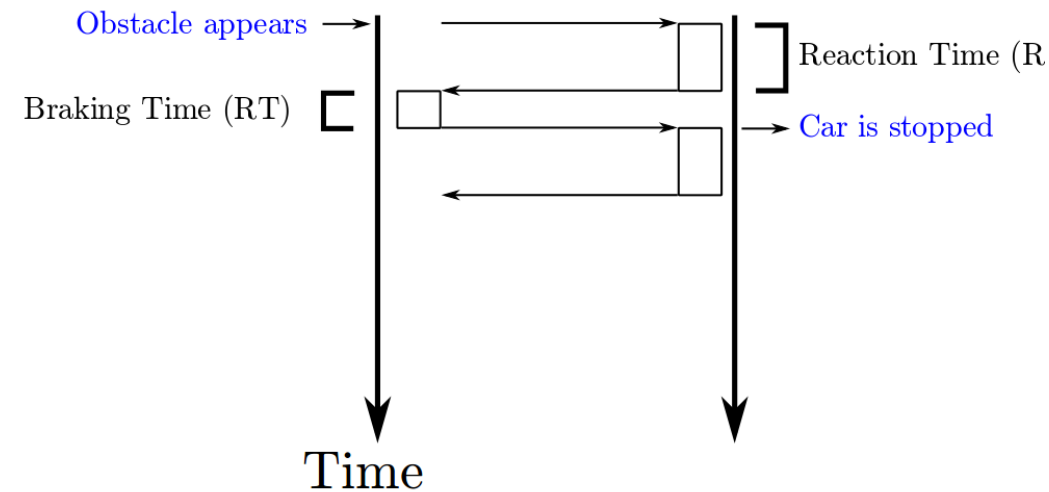
$$BD = v^2 / a$$

What is the minimum RT in town?

($v < 50\text{km/h}$; $OD > 10\text{m}$, $a=14$)

Environment

Driver



Sequence diagram

Real-Time Interaction

In cognitive systems

Real-Time Interaction

In cognitive systems

In vivo

In silico

In vivo

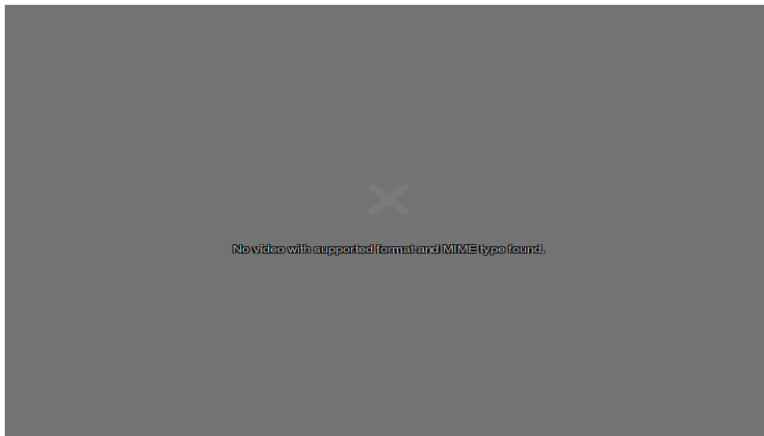
Individual behavior

Group coordination

In vivo

Individual behavior

Head stabilization

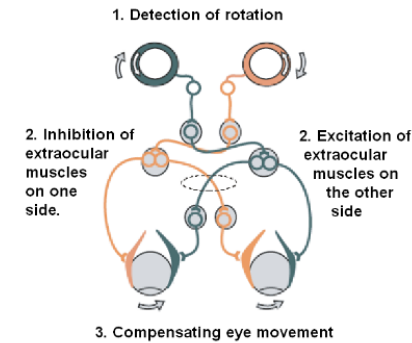
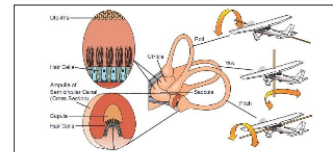
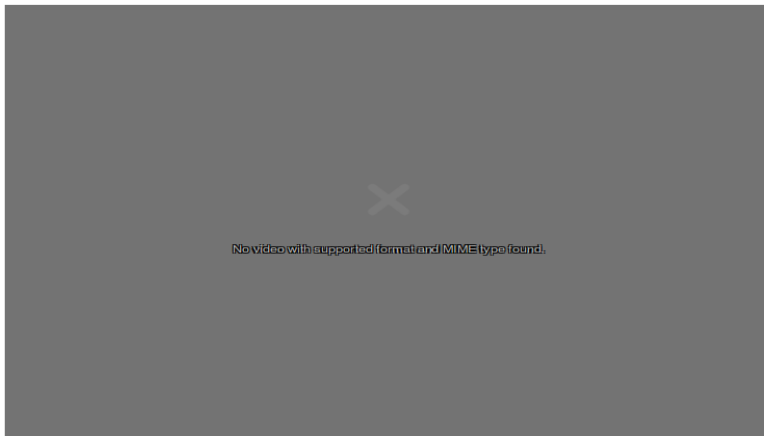


Group coordination

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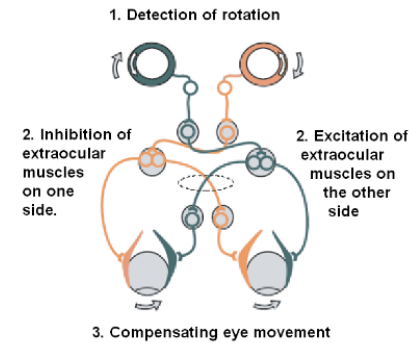
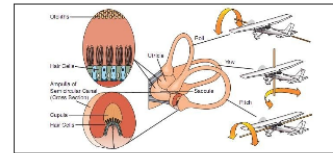
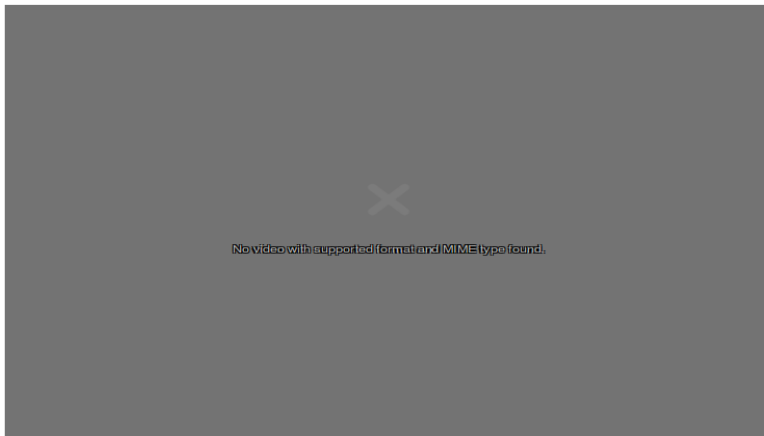


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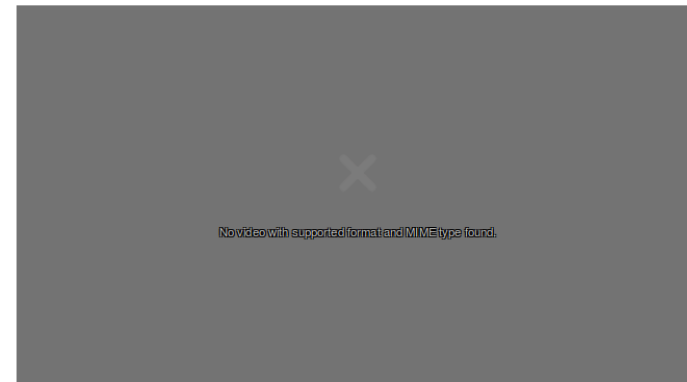
Individual behavior

Head stabilization



Group coordination

V-formation in bird groups



In silico

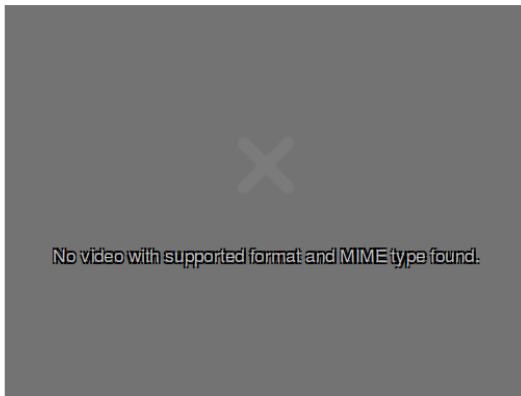
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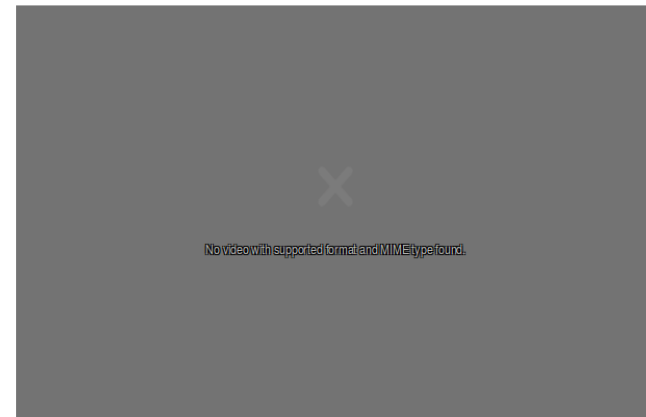
In silico

Individual behavior

Not real-time



Real-time

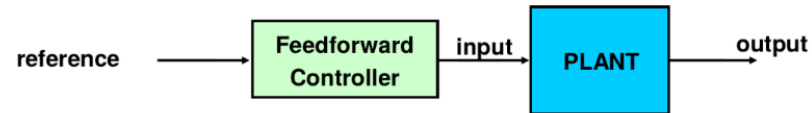


Group coordination

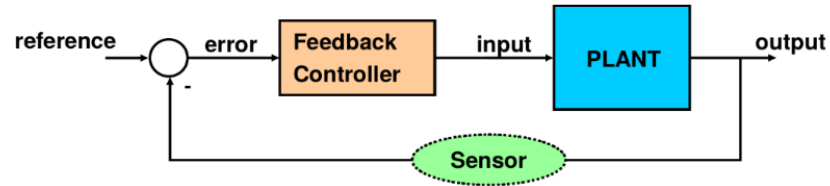
In silico

Individual behavior

- Feedforward control



- Feedback control

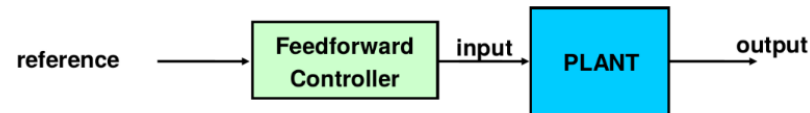


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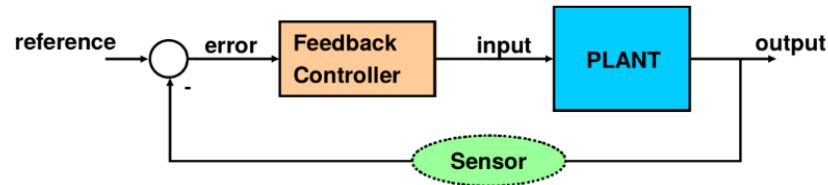
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Individual behavior

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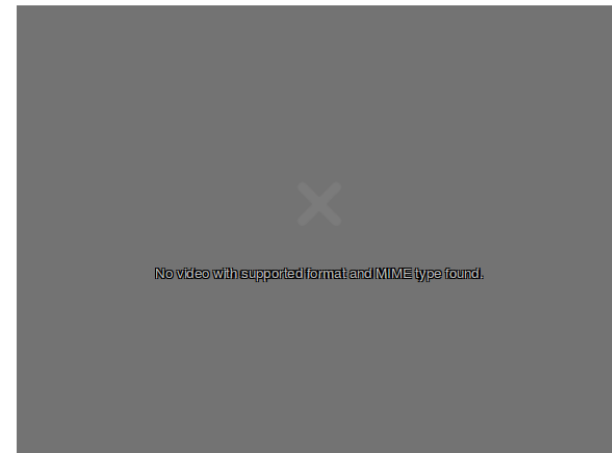


- Feedback control



Group coordination

Self-organization in robotic swarms



Real-Time Interaction

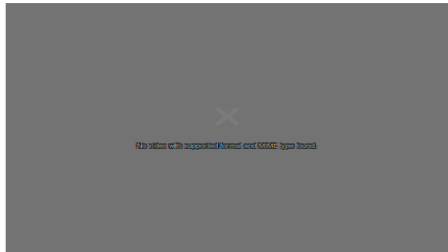
In cognitive systems

In vivo

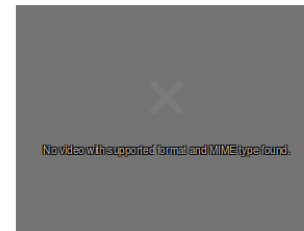
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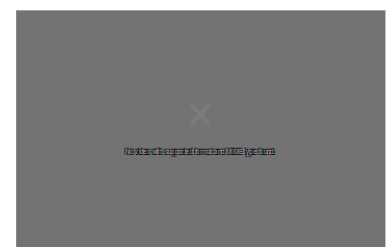
Head stabilization



Not real-time

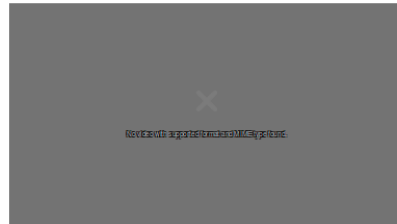


Real-time

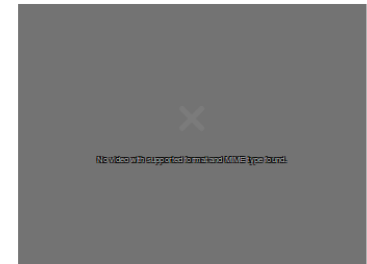


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Real-Time Interaction

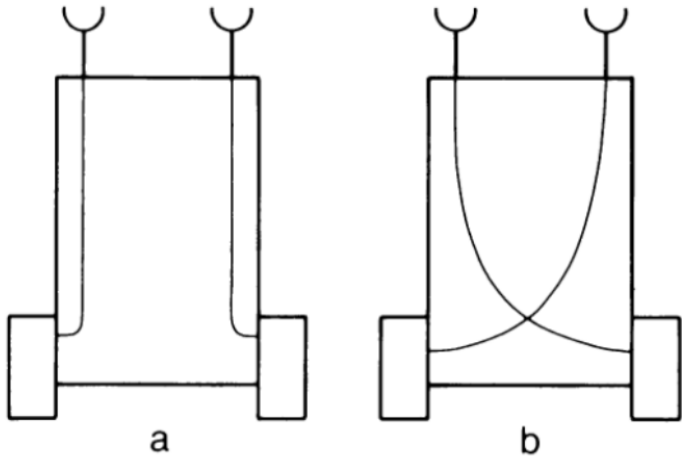
Minimal examples

Real-Time Interaction

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”Vehicles” are quite simple cognitive systems

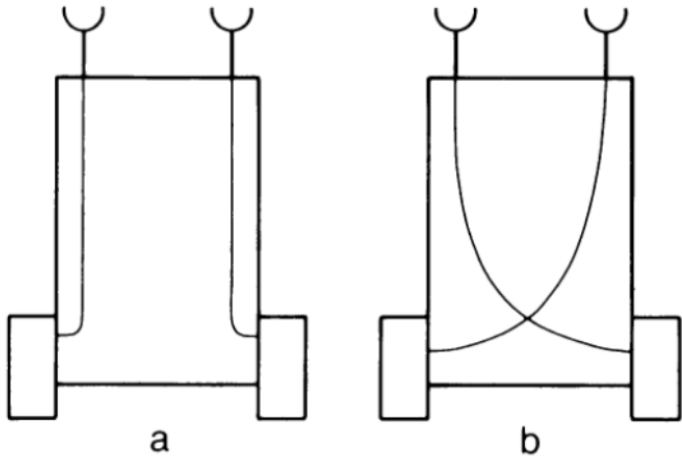


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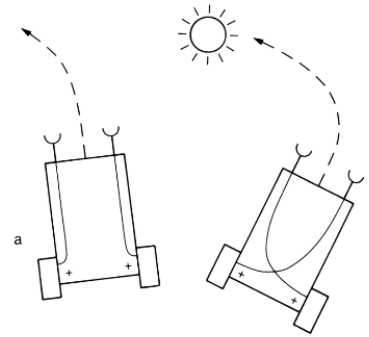
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Fear and aggression

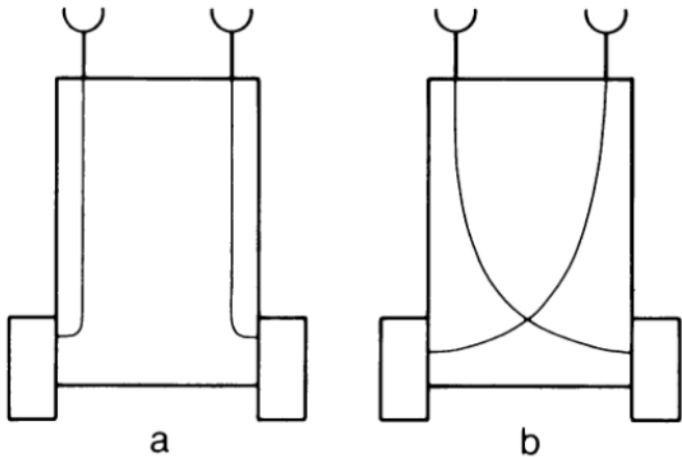


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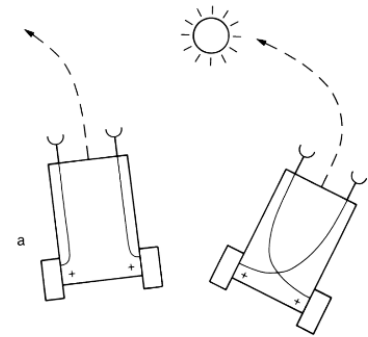
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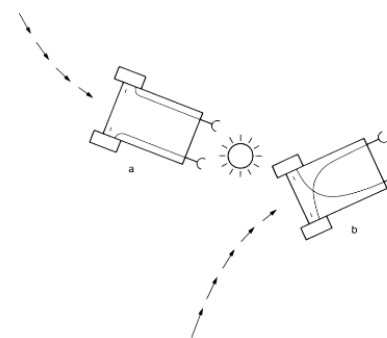
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Fear and aggression



Love

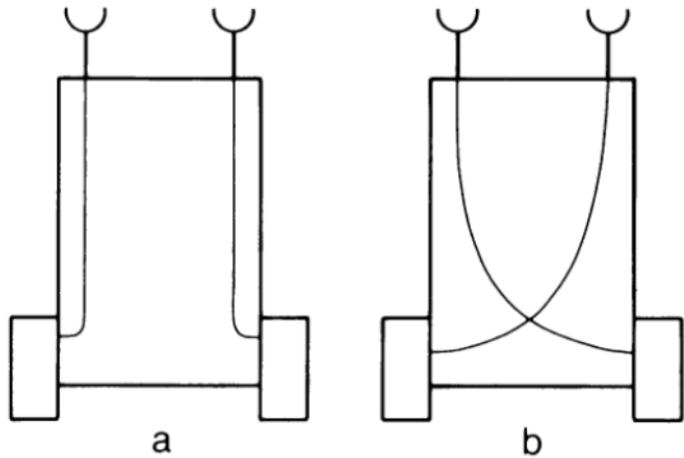


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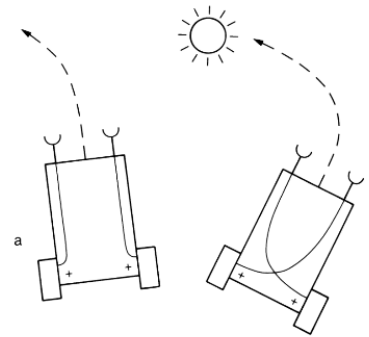
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